

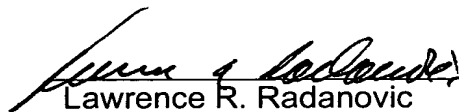
## REMARKS

Combination claim 1 and method claim 7 have been amended to restrict the manipulator to an anthropomorphic manipulator which, as recognized by the examiner, is not the type of manipulator disclosed by the Suzuki et al. 4,529,352 reference, applied as a principle reference against all the claims. Support for the amendment is essentially set forth on page 2 of the present specification, lines 9 to 25, wherein the special problem attending anthropomorphic robots is discussed in some detail. It is this specific problem which the present invention solves in a manner not found or taught by Suzuki et al., or by the Kizer 5,593,265 patent applied as an auxiliary teaching. Moreover, since the upper arm of an anthropomorphic robot rotates about its own longitudinal axis, as pointed out in the last response, and which is clearly not disclosed by Suzuki et al. in that arm 13 pivots only about its inner section with arm 12 (which is not about the longitudinal axis of arm 13), it is believed that no new issues or new considerations are introduced by the amendments to claims 1 and 7. Nor would the claim amendment necessitate a new search. Therefore, it is believed that the amendments qualify for entry after final and it is respectfully requested that the examiner enters these amendments and allow all the claims 1 to 9 in the application.

Respectfully submitted,

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